WHAT WE TALK ABOUT WHEN WE TALK ABOUT DISTRIBUTED SYSTEMS

ALVARO VIDELA

DISTRIBUTED SYSTEMS FOR THE IKEA FAMILY

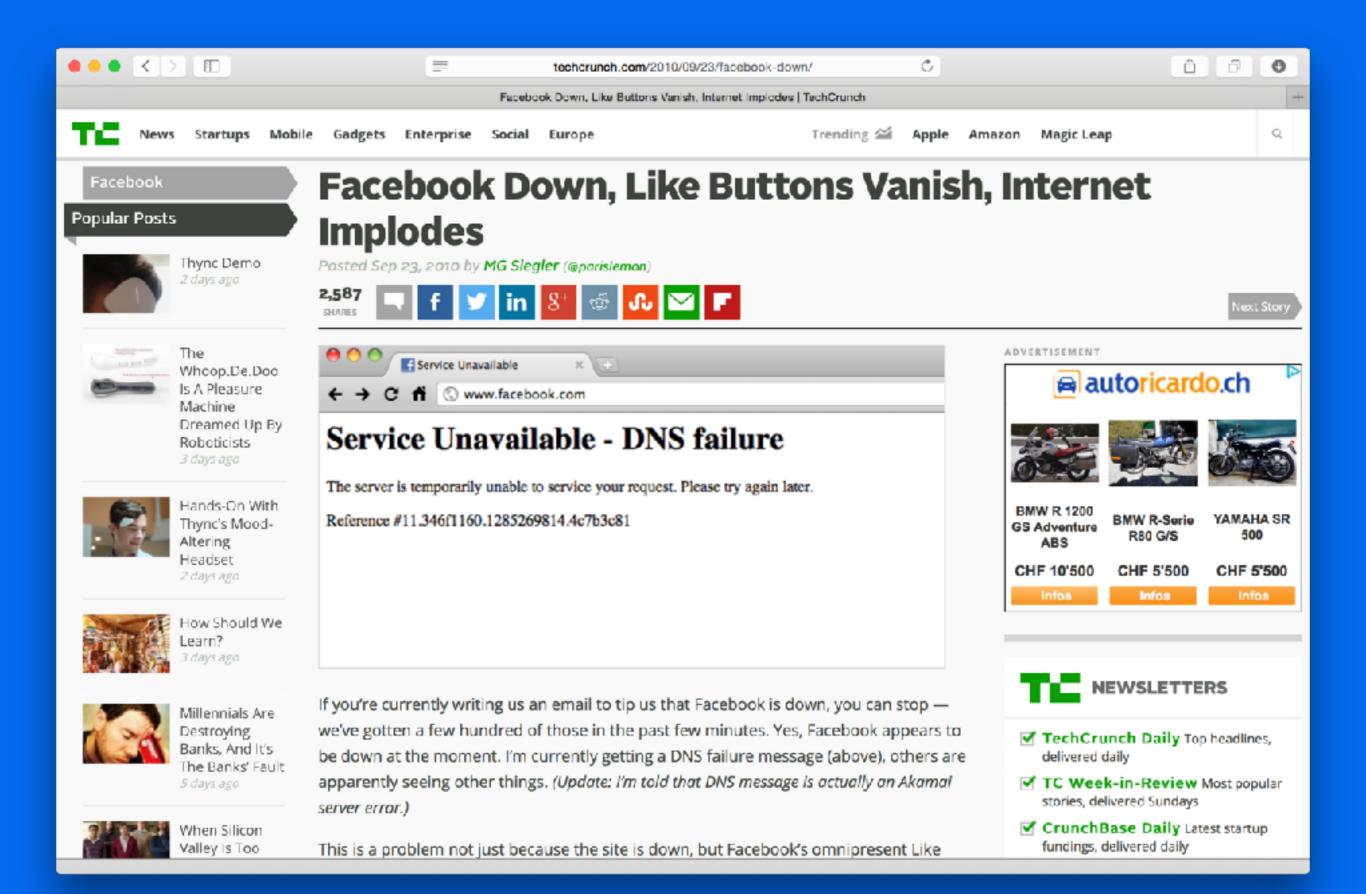
ALVARO VIDELA

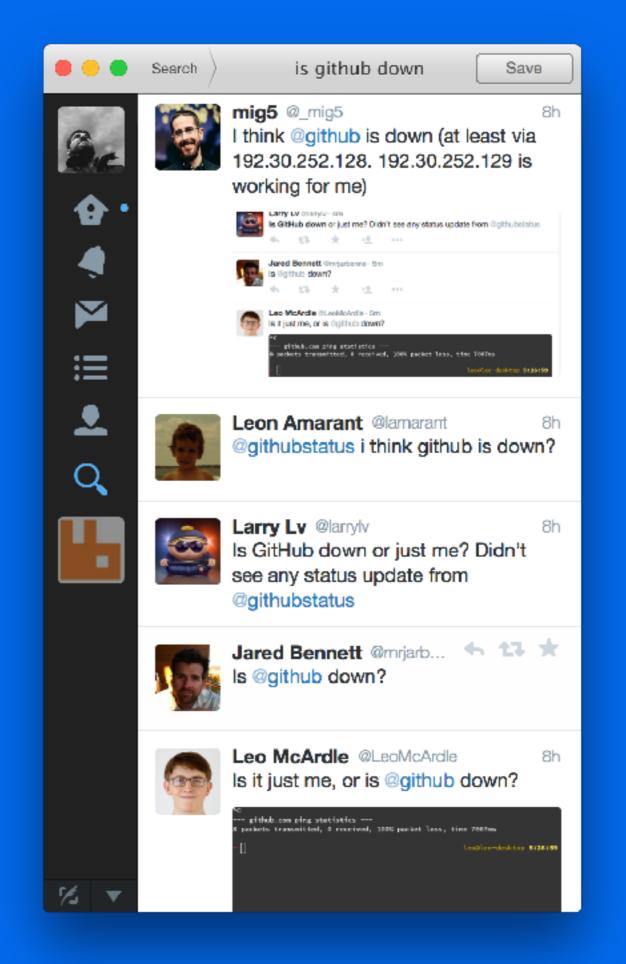
HTTP://BIT.LY/DIST-SYS101

@HINTJENS

"A DISTRIBUTED SYSTEM IS ONE IN WHICH THE FAILURE OF A COMPUTER YOU DID NOT EVEN KNOW EXISTED CAN RENDER YOUR OWN COMPUTER UNUSABLE"

Leslie Lamport





Google: define jargon

jar-gon¹ /'järgən/

noun

special words or expressions that are used by a particular profession or group and are difficult for others to understand.

"legal jargon"

synonyms: specialized language, slang, cant, idiom, argot, patter; More

a form of language regarded as barbarous, debased, or hybrid.

Translations, word origin, and more definitions

 Many entities trying to solve a problem (nodes, processes)

- Many entities trying to solve a problem (nodes, processes)
- Partial Knowledge

- Many entities trying to solve a problem (nodes, processes)
- Partial Knowledge
- Uncertainty

DEEP RABBIT HOLE

WHAT TO READ?

WHICH PAPERS?

Impossibility of Distributed Consensus with One Faulty Process[†]

Michael J Fischer

Nancy A Lynch

Michael S Paterson

Yale University
New Haven, Connecticut

Massachusetts Institute of Technology*
Cambridge, Massachusetts

University of Warwick Coventry, England

Abstract

The consensus problem involves an asynchronous system of processes, some of which may be unrehable. The problem is for the reliable processes to agree on a binary value. We show that every protocol for this problem has the possibility of nontermination, even with only one faulty process. By way of contrast, solutions are known for the synchronous case, the "Byzantine Generals" problem.

A well-known form of the problem is the "transaction commit problem" which arises in distributed database systems [DS1, G, LS, La, Le, Li, R, RLS, S, SS]. The problem is for all the data manager processes which have participated in the processing of a particular transaction to agree on whether to install the transaction's results in the database or to discard them. The latter action might be necessary, for example, if some data managers were for any reason unable to carry out the required transaction processing. Whatever decision is made, all data managers must make the same decision in order to preserve the consistency of the database.



Impossibility of Distributed Consensus with One Faulty Process[†]

Michael J Fischer

Nancy A Lynch

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The Part-Time Parliament

LESLIE LAMPORT
Digital Equipment Corporation

Recent archaeological discoveries on the island of Paxos reveal that the parliament functioned despite the peripatetic propensity of its part-time legislators. The legislators maintained consistent copies of the parliamentary record, despite their frequent forays from the chamber and the forgetfulness of their messengers. The Paxon parliament's protocol provides a new way of implementing the state machine approach to the design of distributed systems.

Categories and Subject Descriptors: C.2.4 [Computer-Communication Networks]: Distributed Systems—network operating systems; D.4.5 [Operating Systems]: Reliability—fault-tolerance; J.1 [Computer Applications]: Administrative Data Processing—government

General Terms: Design, Reliability

Impossibility of Distributed Consensus with One Faulty Process[†]

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Operating Systems R. Stockton Gaines Editor

Time, Clocks, and the Ordering of Events in a Distributed System

Leslie Lamport
Massachusetts Computer Associates, Inc.

The concept of one event happening before another in a distributed system is examined, and is shown to define a partial ordering of the events. A distributed algorithm is given for synchronizing a system of logical clocks which can be used to totally order the events. The use of the total ordering is illustrated with a method for solving synchronization problems. The algorithm is then specialized for synchronizing physical clocks, and a bound is derived on how far out of synchrony the clocks can become.

Key Words and Phrases: distributed systems, computer networks, clock synchronization, multiprocess systems

CR Categories: 4.32, 5.29

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Impossibility of Distributed Consensus wi

Michael J Fischer

Yale University New Haven, Connecticut Nancy A Lynch

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Flavio P. Junqueira Yahoo! Research Barcelona, Catalunya - Spain fpj@yahoo-inc.com

A simple totally ordered broadcast protocol

Abstract

A well-k

"transaction

Operating Systems

R. Stockton Gaines

Editor

Time, Clocks, and the performance. In this paper we present the requirements Zookceper makes on Zab, we show how the protocol is used, Ordering of Events in a Distributed System

Leslie Lamport Massachusetts Computer Associates, Inc.

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ABSTRACT

This is a short overview of a totally ordered broadcast protocol used by ZooKeeper, called Zab. It is conceptually easy to understand, is easy to implement, and gives high and we give an overview of how the protocol works.

ary, for example, if some data r any reason unable to carry out insaction processing all data managers must make the rder to preserve the consistency of chines providing the service and always has a consistent view of the ZooKeeper state. The service tolerates up to f crash failures, and it requires at least 2f + 1 servers.

Applications use ZooKeeper extensively and have tens to thousands of clients accessing it concurrently, so we require high throughput. We have designed ZooKeeper for workloads with ratios of read to write operations that are higher than 2:1; however, we have found that ZooKeeper's

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A simple totally ordered broadcast protocol

Michael J Fischer

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Massachusetts Institute of Technolo Cambridge, Massachusetts

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Flavio P. Junqueira Yahoo! Research Barcelona, Catalunya - Spain fpj@yahoo-inc.com

Abstract

A well-k "transaction A DCTD A CT

Operating Systems

Time, Clo Ordering (Abstract

Leslie Lamport

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In Search of an Understandable Consensus Algorithm

Diego Ongaro and John Ousterhout Stanford University (Draft of May 22, 2013; under submission)

Raft is a consensus algorithm for managing a replicated a Distribu log. It produces a result equivalent to Paxos, and it is as efficient as Paxos, but its structure is different from Paxos; this makes Raft more understandable than Paxos and also provides a better foundation for building practi-Massachusetts Com1 cal systems. In order to enhance understandability, Raft separates the key elements of consensus, such as leader election and log replication, and it enforces a stronger degree of coherency to reduce the number of states that must The concept of one obe considered. Raft also includes a new mechanism for in a distributed system i changing the cluster membership, which uses overlapping define a partial ordering majorities to guarantee safety. Results from a user study algorithm is given for sy demonstrate that Raft is easier for students to learn than

 Strong leader: Raft differs from other consensus algorithms in that it employs a strong form of leadership where only leaders (or would-be leaders) issue requests; other servers are completely passive. This the implementation.

was our most important criterion in evaluating design alternatives. We applied specific techniques to improve understandability, including decomposition (Raft separates leader election, log replication, and safety so that they can be understood relatively independently) and state space reduction (Raft reduces the degree of nondeterminism and the ways servers can be inconsistent with each other, in order to make it easier to reason about the system).

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ervice and always has a consistent view

WHICH BOOKS?

\$ **

Herlihy

Shavit

THE ART OF





Distributed Algorithms

MORGAN KAUFMANN

Lynch



Raynal

Principles, and Foundations

Concurrent Programming: Algorithms,



Raynal

Cachin · Guerraoui Rodrigues

2

Distributed Algorithms for Message-Passing Systems

 $\underline{\mathscr{D}}$

Introduction to Reliable and Secure Distributed Programming

2nd Ed.

Charron-Bost • Pedone Schiper (Eds.)

4

LNCS 5959

Replication

Birman

Guide to Reliable Distributed Systems

REPLICATION TECHNIQUES IN DISTRIBUTED SYSTEMS

UB-980-387

MORGAN & CLAYPOOL

MORGAN&CLAYPOOL

QUORUM SYSTEMS

Poledna

RAYNAL

VUKOLIC

RAYNAL

FAULT-TOLERANT AGREEMENT IN SYNCHRONOUS MESSAGE-PASSING SYSTEMS

COMMUNICATION AND AGREEMENT ABSTRACTIONS FOR FAULT-TOLERANT ASYNCHRONOUS DISTRIBUTED SYSTEMS

DISTRIBUTED COMPUTING LANGUA COMBINATORIAL TOPOLOGY

Herlihy

M<

MORGAN&CLAYPOOL

MULTIPROCESSOR PROGRAMMING

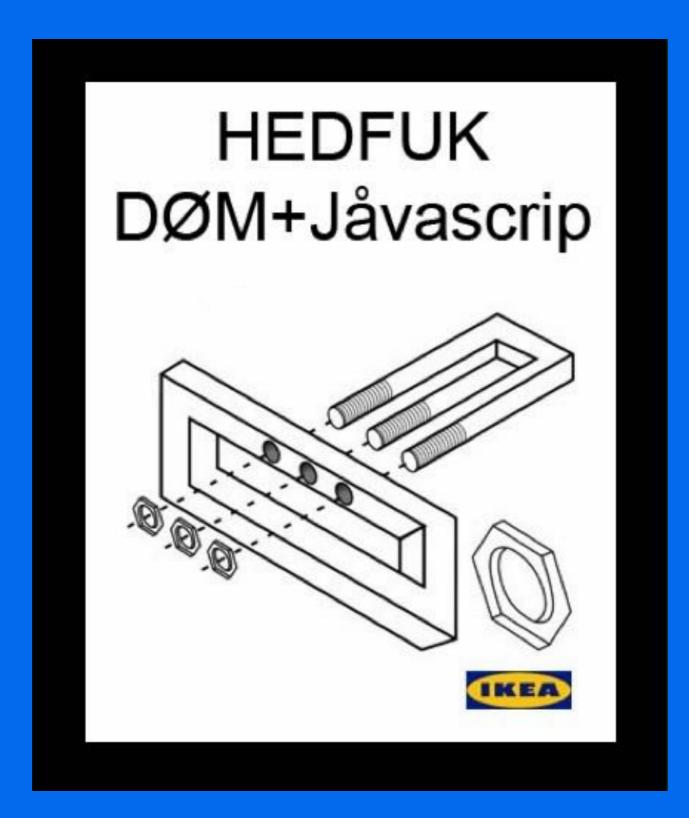
REVISED FIRST EDITION

Programming Distributed Computing Systems

Varela



WHY?



http://tobielangel.com

THE PROBLEM

Timing Model

- Timing Model
- Inter Process Communication Used (IPC method)

- Timing Model
- Inter Process Communication Used (IPC method)
- Failure Modes

Synchronous Model

- Synchronous Model
- Asynchronous Model

- Synchronous Model
- Asynchronous Model
- Semi-synchronous Model

INTERPROCESS COMMUNICATION

INTERPROCESS COMMUNICATION

Message Passing

INTERPROCESS COMMUNICATION

- Message Passing
- Shared Memory

Crash-stop

- Crash-stop
- Crash-recovery

- Crash-stop
- Crash-recovery
- Omission Faults

- Crash-stop
- Crash-recovery
- Omission Faults
- Arbitrary Failures Mode (Byzantine)

LIVENESS AND SAFETY

LIVENESS AND SAFETY PROPERTIES OF ALGORITHMS

DEFINING LIVENESS*

Bowen ALPERN and Fred B. SCHNEIDER

Department of Computer Science, Cornell University, 405 Upson Hall, Ithaca, NY 14853, U.S.A.

Communicated by David Gries Received 5 November 1984 Revised 20 February 1985

A formal definition for liveness properties is proposed. It is argued that this definition captures the intuition that liveness properties stipulate that 'something good' eventually happens during execution. A topological characterization of safety and liveness is given. Every property is shown to be the intersection of a safety property and a liveness property.

SAFETY

Some "bad" thing does not happens during execution

SAFETY

"Communication links should not invent messages out of thin air"

LIVENESS

A "good" thing happens during execution

LIVENESS

"A destination process eventually delivers the message"

LET'S TAKE A LOOK AT FLP¹

1 - Fischer, Lynch, Paterson

Impossibility of Distributed Consensus with One Faulty Process[†]

Michael J Fischer

Nancy A Lynch

Michael S Paterson

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The consensus problem involves an asynchronous system of processes, some of which may be unreliable. The problem is for the reliable processes to agree on a binary value. We show that every protocol for this problem has the possibility of nontermination, even with only one faulty process. By way of contrast, solutions are known for the synchronous case, the "Byzantine Generals" problem

A well-known form of the problem is the "transaction commit problem" which arises in distributed database systems [DS1, G, LS, La, Le, Li, R, RLS, S, SS The problem is for all the data manager processes which have participated in the processing of a particular transaction to agree on whether to install the transaction's results in the database or to discard them The latter action might be necessary, for example, if some data managers were for any reason unable to carry out the required transaction processing Whatever decision is made, all data managers must make the same decision in order to preserve the consistency of the database

In this paper, we show the surprising result that no completely asynchronous consensus protocol can tolerate even a single unannounced process death. We do not consider Byzantine failures, and we assume that the message system is reliable — it delivers all messages correctly and exactly once

Nevertheless, even with these assumptions, the stopping of a single process at an inopportune time can cause any distributed commit protocol to fail to reach agreement. Thus, this important problem has no robust solution without further assumptions about the computing environment or still greater restrictions on the kind of failures to be tolerated!

Crucial to our proof is that processing is completely asynchronous, that is, we make no assumptions about the relative speeds of processes nor about the delay time in delivering a message We also assume that processes do not have access to synchronized clocks, so algorithms based timeouts, for example, cannot be used particular, the solutions in [DS1] are not applicable) Finally, we do not postulate the ability to detect the death of a process, so it is impossible for one process to tell whether another has died (stopped entirely) or is just running very slowly

Our system model is rather strong so as to make our impossibility proof as widely applicable as possible Processes are modelled as automata (with possibly infinitely many states) which communicate by means of messages In one atomic step, a process can attempt to receive a message, perform local computation based on whether or not a message was delivered to it and if so on which one, and send an arbitrary but finite set of messages to other processes In particular, an "atomic broadcast" capability is assumed, so a process can send the same message in one step to all other processes with the knowledge that if any nonfaulty process receives the message, then all the nonfaulty processes will

Every message is eventually delivered as long as the destination process makes infinitely many attempts to receive, but messages can be delayed arbitrarily long and delivered out of order

WHAT'S CONSENSUS ANYWAY?

"THE CONSENSUS PROBLEM IS A PARADIGM OF AGREEMENT PROBLEMS"

https://dl.acm.org/citation.cfm?id=1052796.1052806

• C-Termination: Every correct process eventually decides on some value

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- C-Agreement: No two correct processes decide differently

PROPERTIES OF UNIFORM CONSENSUS

- C-Termination: Every correct process eventually decides on some value
- C-Validity: If a process decides v, then v was proposed by some process
- C-Agreement: No two correct processes decide differently
- C-Uniform Agreement: No two processes (correct or not) decide differently.

WE NEED CONSENSUS WHEN:

A SET OF PROCESSES HAVE TO AGREE TO TAKE A COMMON ACTION

WE NEED CONSENSUS WHEN:

A SET OF PROCESSES HAVE TO AGREE TO TAKE A COMMON ACTION

Atomic Broadcast

WE NEED CONSENSUS WHEN:

A SET OF PROCESSES HAVE TO AGREE TO TAKE A COMMON ACTION

Atomic Broadcast

Group Membership

ATOMIC BROADCAST

"CORRECT PROCESSES DELIVER THE SAME SET OF MESSAGES IN THE SAME ORDER"

FLP TELLS US THAT IF
CONSENSUS CANNOT BE
ACHIEVED, THEN ATOMIC
BROADCAST OR GROUP
MEMBERSHIP CANNOT BE
ACHIEVED EITHER

SO, WE PACK OUR BAGS AND GO?

NOTHING TO SEE HERE?

STUMBLING OVER CONSENSUS RESEARCH:

MISUNDERSTANDING AND ISSUES

Marcos K. Aguilera

FAILURE DETECTORS

Unreliable Failure Detectors for Reliable Distributed Systems

TUSHAR DEEPAK CHANDRA

I.B.M. Thomas J. Watson Research Center, Hawthorne, New York

AND

SAM TOUEG

Cornell University, Ithaca, New York

We introduce the concept of unreliable failure detectors and study how they can be used to solve Consensus in asynchronous systems with crash failures. We characterise unreliable failure detectors in terms of two properties—completeness and accuracy. We show that Consensus can be solved even with unreliable failure detectors that make an infinite number of mistakes, and determine which ones can be used to solve Consensus despite any number of crashes, and which ones require a majority of correct processes. We prove that Consensus and Atomic Broadcast are reducible to each other in asynchronous systems with crash failures; thus, the above results also apply to Atomic Broadcast. A companion paper shows that one of the failure detectors introduced here is the weakest failure detector for solving Consensus [Chandra et al. 1992].

FAILURE DETECTORS

External process

- External process
- Provides information about suspected processes

- External process
- Provides information about suspected processes
- Completeness property (crashed processes are detected)

- External process
- Provides information about suspected processes
- Completeness property (crashed processes are detected)
- Accuracy (correct process are never suspected)

"RUB SOME PERFECT FAILURE DETECTOR ON IT"

PERFECT FAILURE DETECTOR

Module 2.6: Interface and properties of the perfect failure detector

Module:

Name: PerfectFailureDetector, instance \mathcal{P} .

Events:

Indication: $\langle \mathcal{P}, Crash \mid p \rangle$: Detects that process p has crashed.

Properties:

PFD1: Strong completeness: Eventually, every process that crashes is permanently detected by every correct process.

PFD2: Strong accuracy: If a process p is detected by any process, then p has crashed.

http://www.amazon.com/Introduction-Reliable-Secure-Distributed-Programming/dp/3642152597

• Strong Completeness: Eventually, every process that crashes is permanently suspected by every correct process.

- Strong Completeness: Eventually, every process that crashes is permanently suspected by every correct process.
- Eventual Weak Accuracy: There is a time after which some correct process is never suspected by the correct processes.

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http://dl.acm.org/citation.cfm?id=1052806

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TL;DR:

INTERSECTING SETS

"A QUORUM IN A SYSTEM WITH N
CRASH-FAULT PROCESS ABSTRACTIONS
[...] IS ANY MAJORITY OF
PROCESSES, I.E., ANY SET OF MORE
THAN N/2 PROCESSES"

"IF F < N/2 PROCESSES FAIL BY CRASHING, THERE IS ALWAYS AT LEAST ONE QUORUM OF NONCRASHED PROCESSES IN SUCH SYSTEMS"

A - B - C - D - E

CONSISTENCY

Linearizability: A Correctness Condition for Concurrent Objects

MAURICE P. HERLIHY and JEANNETTE M. WING Carnegie Mellon University

A concurrent object is a data object shared by concurrent processes. Linearizability is a correctness condition for concurrent objects that exploits the semantics of abstract data types. It permits a high degree of concurrency, yet it permits programmers to specify and reason about concurrent objects using known techniques from the sequential domain. Linearizability provides the illusion that each operation applied by concurrent processes takes effect instantaneously at some point between its invocation and its response, implying that the meaning of a concurrent object's operations can be given by pre- and post-conditions. This paper defines linearizability, compares it to other correctness conditions, presents and demonstrates a method for proving the correctness of implementations, and shows how to reason about concurrent objects, given they are linearizable.

CONCURRENT FIFO QUEUE

Atomic Consistency (Linearizabilty)

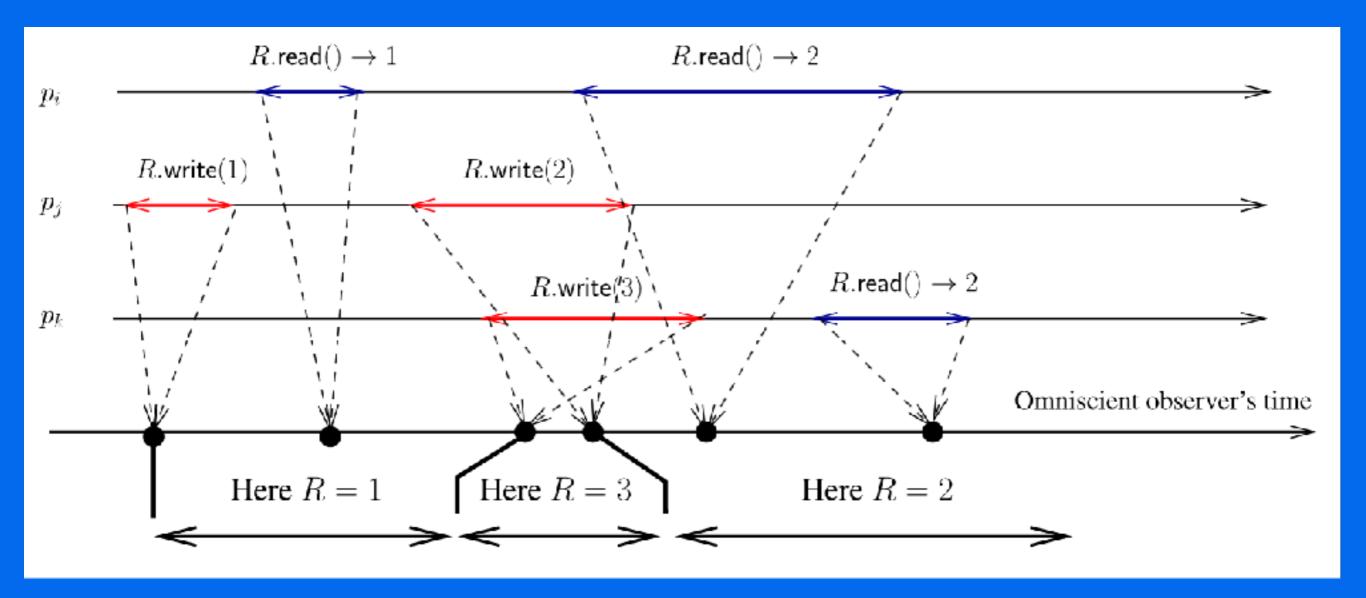
- Atomic Consistency (Linearizabilty)
- Sequential Consistency

- Atomic Consistency (Linearizabilty)
- Sequential Consistency
- Causal Consistency

- Atomic Consistency (Linearizabilty)
- Sequential Consistency
- Causal Consistency

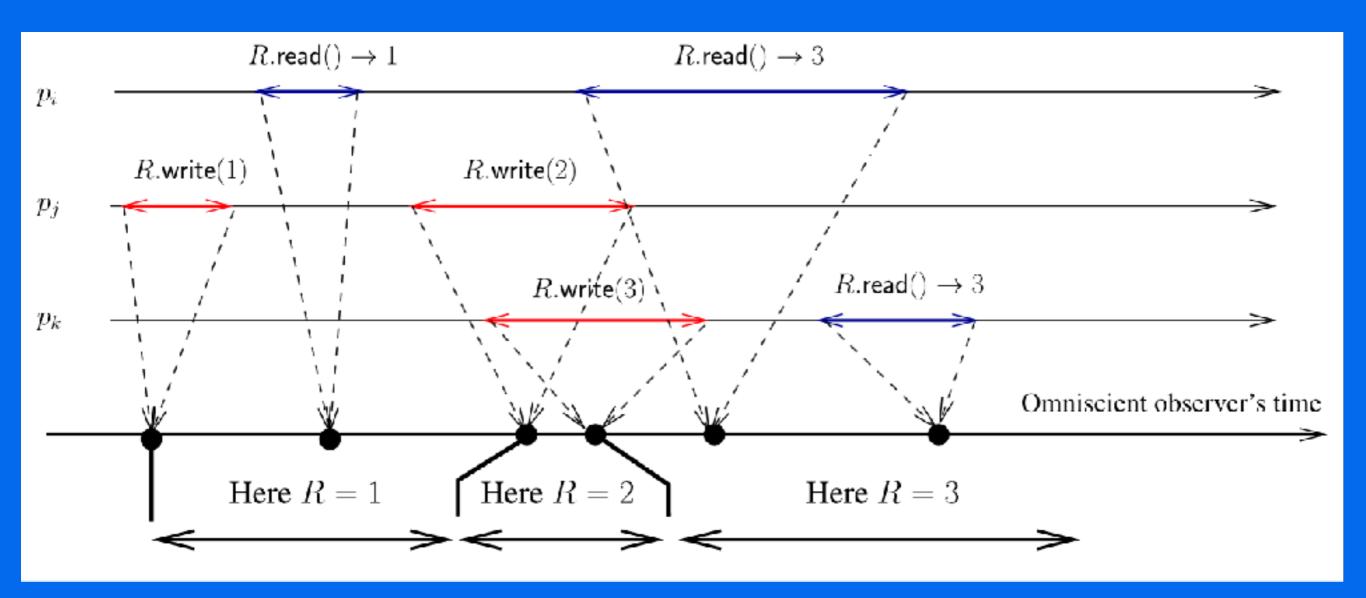
https://aphyr.com/posts/313-strong-consistency-models

LINEARIZABILTY



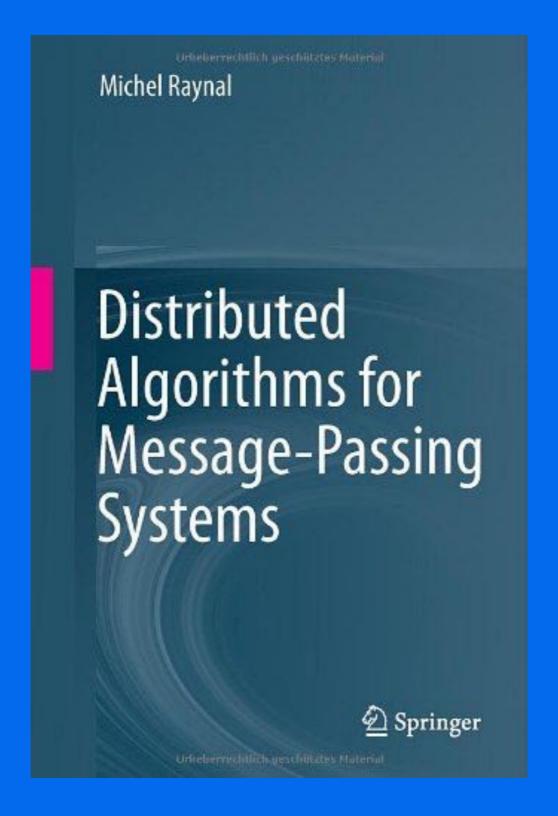
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LINEARIZABILTY



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Fault-tolerant Agreement in Synchronous Message-passing Systems

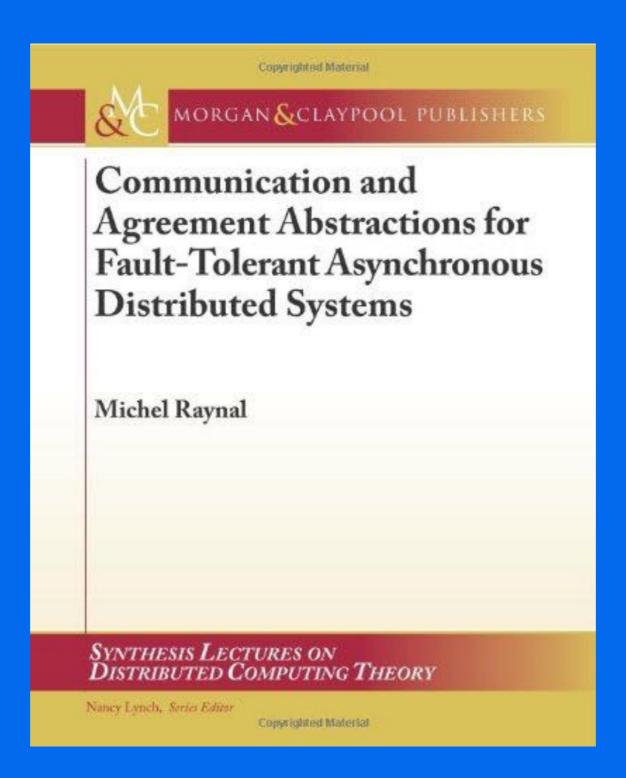
Michel Raynal

SYNTHESIS LECTURES ON DISTRIBUTED COMPUTING THEORY

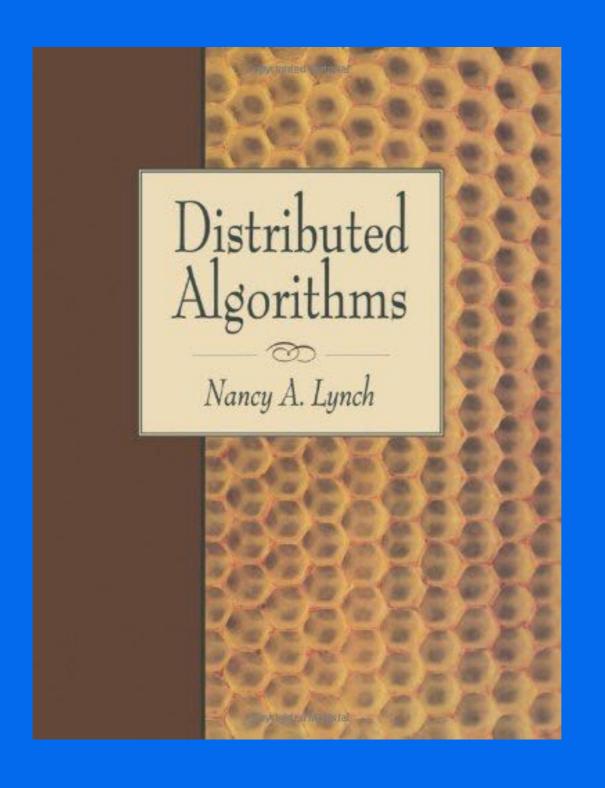
Nancy Lynch, Series Editor

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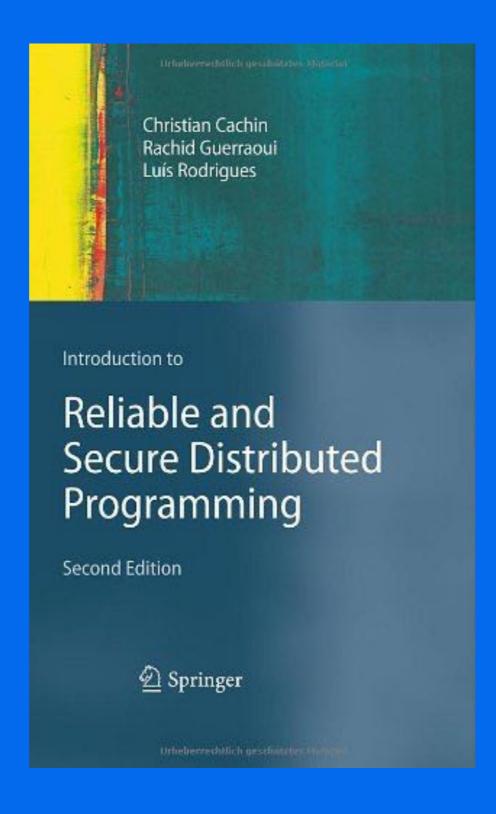
http://www.amazon.com/Fault-tolerant-Agreement-Synchronous-Message-passing-Distributed/dp/
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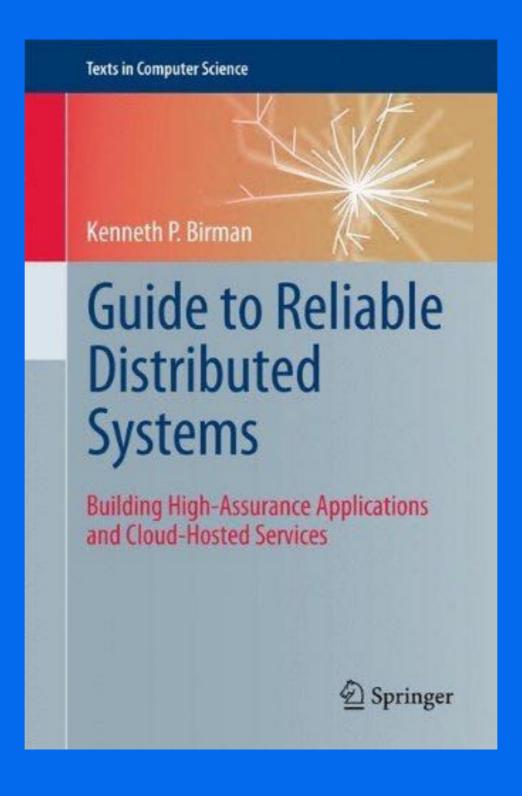
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http://www.amazon.com/Guide-Reliable-Distributed-Systems-High-Assurance/dp/1447124154/ State-of-the-Art Survey

Bernadette Charron-Bost Fernando Pedone André Schiper (Eds.)

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Theory and Practice



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- History of the Field Matters

- Deep Rabbit Hole
- Computing Science where Science is Still a Thing™
- History of the Field Matters
- Read, read, read

THANKS!

@old_sound